# PyroMiniUSB Series Operator's Guide





The PyroMiniUSB is a simple, compact infrared temperature sensor with USB communications. It measures the surface temperature of a variety of materials without contact. The available free software is intuitive and easy to use, and the open Modbus protocol allows users to connect directly to the sensor using software of their own design.

The sensor's rugged construction makes it ideal for benchtop, laboratory and education applications.

# SPECIFICATIONS

Field of View		Model Number	
2:1 wide-angle optics		PMU21	
20:1 general-purpose optics		PMU201	
Close Focus optics (Ø 3.5 mm at 50 mm distance)		PMUXCF	
Interface	USB		
Accuracy ±1% of reading or ±1°C which		er is greater	
Repeatability	± 0.5% of reading or ± 0.5°C whi	chever is greater	
Emissivity	0.2 to 1.0		
Response Time	125 ms (90% response)		
Spectral Range	8 to 14 μm		
Supply Voltage	5 V DC (provided by USB)		
Supply Current	50 mA max.		

#### VIRTUAL COM PORT

Baud Rate	9600 baud *	
Format	8 data bits, no parity, 1 stop bit *	
Protocol Modbus over Serial Line		
* Other configurations available upon request		

\* Other configurations available upon request

## CONFIGURATION

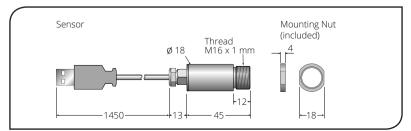
Configuration Method	Via USB using free CalexConfig software or Modbus
Configurable Parameters	Emissivity Setting, Averaging, Reflected Energy Compensation

#### MECHANICAL

Construction	Stainless Steel
Dimensions	18 mm diameter x 45 mm long (excluding cable gland)
Thread Mounting	M16 x 1 mm pitch
Cable Length	1.45 m
Weight	100 g

#### **ENVIRONMENTAL**

Environmental Rating	IP65
Ambient Temperature	0°C to 75°C
Relative Humidity	95% max. non-condensing



# ACCESSORIES

A range of accessories to suit different applications and environments is available. These may be ordered at any time and added on-site. The following accessories are available:

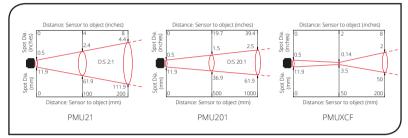
Fixed and Adjustable Mounting Brackets, Air Purge Collar, Laser Sighting Tool

# OPTIONS

An optional certificate of calibration is available for newly-manufactured sensors. If required, it must be ordered at the same time as the sensor.

# OPTICS

The optical charts below show the target spot diameter at any given distance from the sensor, and assume 90% energy. Sensors may also be used at longer distances.



## INSTALLATION

The installation process consists of the following stages:

- 1 Preparation
- 2 Mechanical Installation
- 3 Software Installation

Please read the following sections thoroughly before proceeding with the installation.

## PREPARATION

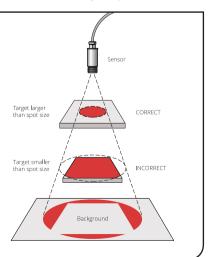
Ensure that the sensor is positioned so that it is focused on the target only.

# DISTANCE AND SPOT SIZE

The size of the area (spot size) to be measured determines the distance between the sensor and the target.

The spot size must not be larger than the target. The sensor should be mounted so that the measured spot size is smaller than the target.

We normally recommend the target should be at least twice the size of the measured spot for maximum accuracy.



## AMBIENT TEMPERATURE

The sensor is designed to operate in ambient temperatures from 0°C to 75°C. Avoid thermal shock. Allow 20 minutes for the unit to adjust to large changes in ambient temperature.

## ATMOSPHERIC QUALITY

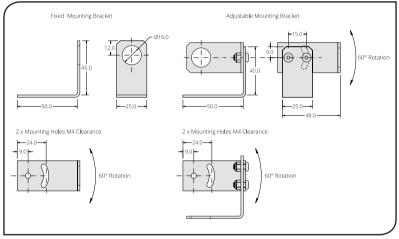
Smoke, fumes or dust can contaminate the lens and cause errors in temperature measurement. In these types of environment the air purge collar should be used to help keep the lens clean.

## **ELECTRICAL INTERFERENCE**

To minimise electromagnetic interference or 'noise', the sensor should be mounted away from motors, generators and such like.

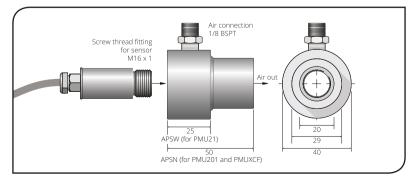
# MECHANICAL INSTALLATION

All sensors are supplied with a 1.45 m USB cable and a mounting nut. The sensor can be mounted on brackets, clamps or cut outs of your own design, or you can use the fixed and adjustable mounting bracket accessories, which are shown below.



## AIR PURGE COLLAR

The air purge collar is used to keep dust, fumes, moisture, and other contaminants away from the lens. It must be screwed in fully. Air flows into the 1/8" BSP fitting and out of the front aperture. Air flow should be 5 to 15 litres/min. Clean or 'instrument' air is recommended.



#### SOFTWARE

The sensor may be used with the free CalexConfig software, or third- party Modbus software.

See MODBUS OVER SERIAL LINE for details of the Modbus registers.

#### System Requirements:

Windows Vista or newer

USB 2.0 port

Internet access (for software download)



#### Installation

NOTE: Do not connect the sensor until the software has been fully installed. The software will tell you when to connect the sensor. This will ensure the USB driver for the sensor is installed properly.

- 1 Download the Calex software free of charge at <u>www.calex.co.uk/software</u>.
- 2 Unzip the files and run Setup.exe.
- 3 Follow the on-screen instructions.

#### Using the Software for the First Time

1. After the software has been installed, when prompted, connect the sensor to an available USB 2.0 port.

2. Start Calex software using the desktop icon.

#### OPERATION

Once the sensor is in position, the software installed and the sensor connected via USB, the system is ready for continuous operation.

## IMPORTANT

Be aware of the following when using the sensor:

- If the sensor is exposed to significant changes in ambient temperature (hot to cold, or cold to hot), allow 20 minutes for the temperature to stabilise before taking or recording measurements.
- Do not operate the sensor near large electromagnetic fields (e.g. around arc welders or induction heaters). Electromagnetic interference can cause measurement errors.

## SOFTWARE FUNCTIONS (CALEXCONFIG)

#### **Temperature Units**

Click °C or °F to switch between Celsius and Fahrenheit.

#### Graph

The graph is a scrolling chart of the measured temperature.

#### Unlocking the Software

The software settings are locked by default. To unlock the software, click the Unlock icon, enter the password, then click the Unlock icon again.

The default password is 1234. This can be changed on the Lock/Unlock screen.

#### Settings

The sensor is fully configurable via the Settings menu.

#### **Output Processing**

The sensor has a response time of 125 ms. If this is too fast, or to minimise the the effects of temperature fluctuations or noise on the measurement, the averaging period can be set between 0 and 60 seconds.

If required, hold processing can be applied by setting Hold Mode to "Peak" or "Valley" and setting the hold period. This is useful if the temperature reading is interrupted by gaps between moving objects, or by an obstruction.

#### **Emissivity Setting**

Enter the desired emissivity setting here. Emissivity can be set between 0.2 and 1.0.

For an accurate temperature reading, the sensor's emissivity setting should match the actual emissivity of the target surface.

Non-reflective non-metals, such as rubber, foods, thick plastics, organic materials and painted surfaces, generally have a high emissivity, around 0.95. This is the default setting.

Bare, clean metal surfaces can have a very low emissivity, and are often difficult to measure accurately. If possible, a measurable area of the surface should be painted or coated to reduce reflections and increase the emissivity.

For more information about emissivity, contact Calex.

#### **Reflected Energy Compensation**

In most applications, the target surface has the same surroundings as the sensor (for example, it is in the same room). In this case, Reflected Energy Compensation should remain disabled for an accurate measurement.

However, if the sensor is positioned outside an oven or furnace, with the target surface inside, the reflection of the hot furnace interior can affect the measurement. In this case, Reflected Energy Compensation should be enabled, and set to the temperature inside the oven or furnace.

## Data Logging

Data can be logged to a comma-separated text file, which can be opened in Excel for analysis. The fastest possible sample rate is 1 reading per second.

## MODBUS OVER SERIAL LINE

#### Interface

Baud rate	9600
Format	8 data, No parity, 1 stop bit
Reply delay (ms)	20

## Supported Functions

Read register	0x03, 0x04
Write single register	0x06
Write multiple register	0x10
Mask write register	0x17

## LIST OF MODBUS REGISTERS

The list below includes all available addresses.

R = Read, W = Write

Address	Length (words)	Description	R/W
0x00	1	Sensor Type (16 for PyroMiniUSB, 17 for PyroMiniBus)	R
0x01	1	Field of view	R
		0 for 2:1; 1 for 20:1; 2 for XCF	
0x02	2	Serial number	R
0x04	1	Modbus slave address (default: 1)	R/W
0x05	1	Reflected Energy Compensation	R/W
		0 for Off; 1 for On	
0x06	1	Reflected Temperature	R/W
0x07	1	Emissivity (1 LSB = 0.0001)	R/W
		Minimum 0.2000, Maximum 1.0000	
0x08	1	Hold Mode	R/W
		0 for Off; 1 for Peak; 2 for Valley	
0x09	1	Hold Period (1 LSB = 0.1 seconds)	R/W
		Minimum 0.1 seconds, Maximum 1200.0 seconds	
0x0A	1	Average Period (1 LSB = 0.1 seconds)	R/W
		Minimum 0.1 seconds, Maximum 60.0 seconds	
0x0B	1	Average Temperature	R
0x0C	1	Minimum Temperature	R
0x0D	1	Maximum Temperature	R
0x0E	1	Filtered Temperature	R
0x0F	1	Unfiltered Temperature	R
0x10	1	Sensor Temperature	R
0x11	1	Status (bits active high)	R
		Bit 0: Measurement error	
		Bit 1: Sensor temperature low	
		Bit 2: Sensor temperature high	
		Bit 3: Object temperature low	
		Bit 4: Object temperature high	
0x16	1	Reflected Temperature (not saved to non-volatile memory)	R/W
0x17	1	Emissivity (not saved to non-volatile memory)	R/W

Notes:

1. All temperature are in tenths of degrees C

2. With the exception of addresses 0x16 and 0x17, all write operations are saved to non-volatile memory

3. For further information please refer to http://www.modbus.org/specs.php

4. Use address 255 to communicate with any connected sensor (only one sensor connected)

5. Use address 0 to broadcast to all connected sensors (no response expected)

#### MAINTENANCE

Our customer service representatives are available for application assistance, calibration, repair, and solutions to specific problems. Contact our Service Department before returning any equipment. In many cases, problems can be solved over the telephone. If the sensor is not performing as it should, try to match the symptom below to the problem. If the table does not help, call Calex for further advice.

## TROUBLESHOOTING

Symptom	Probable Cause	Solution
Sensor cannot be found, or software will not start	Software or USB driver failed to install properly	Disconnect sensor. Uninstall software. Reinstall as Administrator (right-click the installer and select "Run As Administrator"). Do not connect the sensor until prompted by the installer.
Software will not start, or will not install	Incompatible Windows version	Check System Requirements: CalexConfig software requires Windows Vista or newer.
Inaccurate measured temperature	Field of view obstruction	Remove obstruction; ensure sensor has a clear view of target
	Target too small for sensor's field of view	Ensure the sensor's view is completely filled by the target. Position the sensor closer to the target to measure a smaller area.
	Target is a reflective metal surface	Use a lower emissivity setting, or measure a non-reflective area, or paint or coat a measurable area of the target to make it non-reflective
	Dust or condensation on lens	Ensure lens is clean and dry. Clean gently with a soft lens cloth and water. If problem recurs, consider using an air purge collar.

## LENS CLEANING

Keep the lens clean at all times. Any foreign matter on the lens would affect measurement accuracy. Blow off loose particles (if not using the air purge accessory) with an air 'puffer'.

#### GUARANTEE

Calex guarantees each instrument it manufactures to be free from defect in material and workmanship under normal use and service for the period of two years from the date of purchase. This guarantee extends only to the original buyer according to Calex Terms and Conditions of Sale.

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